

# KRISTY SAKANO

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## EDUCATION

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### University of Maryland at College Park

Ph.D. Student, Department of Computer Science

Advisor: Dr. Mumu Xu, Department of Aerospace Engineering

College Park, Maryland

*August 2023 - In Progress*

### Georgia Institute of Technology

M.S. in Computer Science, Specialization in Computational Perception & Robotics

Atlanta, Georgia

*January 2020 - May 2023*

### University of North Carolina at Chapel Hill

B.S. in Physics, Option Astrophysics

Chapel Hill, North Carolina

*August 2014 - May 2018*

## RESEARCH

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### UMD Department of Aerospace Engineering, Xu Lab

College Park, MD

*Qualifying Autonomous Systems: Learning from Mario Kart for Robust Safety*

July 2024 - Present

- Developed a framework integrating parametric Signal Temporal Logic (pSTL) to ensure deep reinforcement learning policies comply with human-readable specifications.
- Implemented and tested an autonomous agent in Super Mario Kart using Proximal Policy Optimization (PPO) to evaluate safety constraints in a structured driving environment.
- Incorporated explainable AI techniques and sensitivity analysis to enhance policy transparency, bridging formal methods with data-driven learning for autonomous systems.

## WORK & INTERNSHIPS

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### Graduate Research Intern at START

College Park, Maryland

*June 2025 - August 2025*

**Summer 2025** - Conducted an independent research project analyzing the evolving threat landscape of ideologically motivated cyberattacks (hacktivism) as part of a national security internship program at the National Consortium for the Study of Terrorism and Responses to Terrorism (START)

### Operations Research Analyst at NAWCAD

AI & Autonomy Applications Division

*Patuxent River, Maryland*

*August 2018 - August 2024*

- **FY19-FY24** - project lead for three internal NAWCAD autonomous systems development projects. Topics include multi-agent autonomous decision making (task allocation, cooperative search, etc), multi-domain autonomy, operations in comms denied environments, and more. Information material subject to Distribution C release.

### Research Intern at NASA Goddard

Science Data Processing Branch, Code 587

*Greenbelt, MD*

*January 2021 - July 2021*

- **FY21** - Collaborated with NASA researchers to develop a unique Linux build and testing platform to evaluate communications-limited deep learning algorithms on Xilinx's Zybo. Performed benchmark analysis to cross-compare the FPGA performance with other development boards and application specific integrated circuits with regards to accuracy, speed, memory usage, and performance. Trained a new classified hyperspectral dataset to develop a TFLite model integrable with the Zybo platform.

### Research Intern at NRL

Distributed Autonomous Systems Group, Code 5514

*Washington, D.C.*

*September 2019 - December 2019*

- **FY20** - Collaborated with NRL researchers on a cross-organizational project focused on herding of non-cooperative robots in complex environments. Simulated and experimentally validated a previously proposed approach for a pursuer-evader strategy involving navigation around convex obstacles to a goal location.

## PUBLICATIONS AND PRESENTATIONS

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### Publications

- **K. Sakano**, J. Mockler, A. Chen and H. Xu, "A Framework for Black-Box Controller Design to Automatically Satisfy Specifications Using Signal Temporal Logic," 2025 International Conference on Unmanned Aircraft Systems (ICUAS), Charlotte, NC, USA, 2025, pp. 587-594, doi: 10.1109/ICUAS65942.2025.11007815.
- J.S. Goodwill, J.P. MacKinnon, **K. Sakano**, C.M. Wilson (2022). Onboard hyperspectral image classification via transfer learning for communication-limited spacecraft. 2022 IEEE Aerospace Conference (AERO), 1-13
- G. Torres and **K. Sakano**, " $\eta$  Geminorum: an eclipsing semiregular variable star orbited by a companion surrounded by an extended disc," Monthly Notices of the Royal Astronomical Society, vol. 516, no. 2, pp. 2514–2521, Aug. 2022, doi: 10.1093/mnras/stac2322.
- G. Arreaga, M. Creech, and **K. Sakano** (2021). Performative Analysis of Sensor Limitations in Communication Denied Environments. 2021 Military Sensing Symposium. Refereed.
- **K. Sakano** and V. Edwards. (2020). Pursuit evasion of a swarm using A\* path planning. Unclassified, released under Distro A through the Naval Research Laboratory.

### Presentations

- Oral Presentation, Int'l Conference on Unmanned Aircraft Systems (ICUAS) May 2025
- Oral Presentation, NAWCAD Symposium for Emerging Professionals (NSEP)\* July 2023
- Poster Presentation, Naval Applications of Machine Learning (NAML) February 2023
- Oral Presentation, DoD 6.1 Basic Research Conference September 2022
- Oral Virtual Presentation, NSEP July 2022
- Oral Virtual Presentation, NAML February 2022
- Oral Virtual Presentation, NSEP July 2021
- Oral Virtual Presentation, Military Sensing Symposium Joint (BAMS and NSSDF) Conference December 2021
- Virtual Poster Presentation, NSEP\* July 2020
- Poster Presentation, NAML February 2020

\* Received Best Presentation Award at NSEP for outstanding DoD research.

## TEACHING

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### UMD Department of Computer Science

*Graduate Teaching Assistant for CMSC 434: Introduction to HCI*

College Park, MD

*August 2023 - Present*

- Taught the basics of Human-Computer Interaction (HCI) to over 350 students across 3 semesters
- Provided one-on-one iterative feedback to student teams developing an app prototype as part of the course project
- Worked with the instructor to create new problem contexts and questions for in-class exams